



MICE Magnet Modelling - Presentation to Vector Fields (Cobham)

RAL
13th March 2013



Overview of MICE



Overview of MICE

The MICE experiment uses a beam of low energy muons to test the feasibility of ionization cooling.

The goal of the MICE experiment is to construct a section of cooling channel long enough to demonstrate a measurable cooling effect.

This is achieved by reducing the transverse emittance of a muon beam by the order of 10%. Several different particle detectors will be used to measure the cooling effect particle by particle with high precision, the aim being to achieve an absolute accuracy on the measurement of emittance of 0.1% or better.

The emittance measurements will be performed with muon beams of different momenta within the range of 140 to 240 MeV/c *and a variety of beam optics and absorber materials will be tried.*

Much of the primary beamline for the experiment has been constructed and commissioned and work is now focusing on installing the major components of the cooling channel.



Overview of MICE

We have a beamline to 'feed' the experiment:

Target

3 Quad Triplets

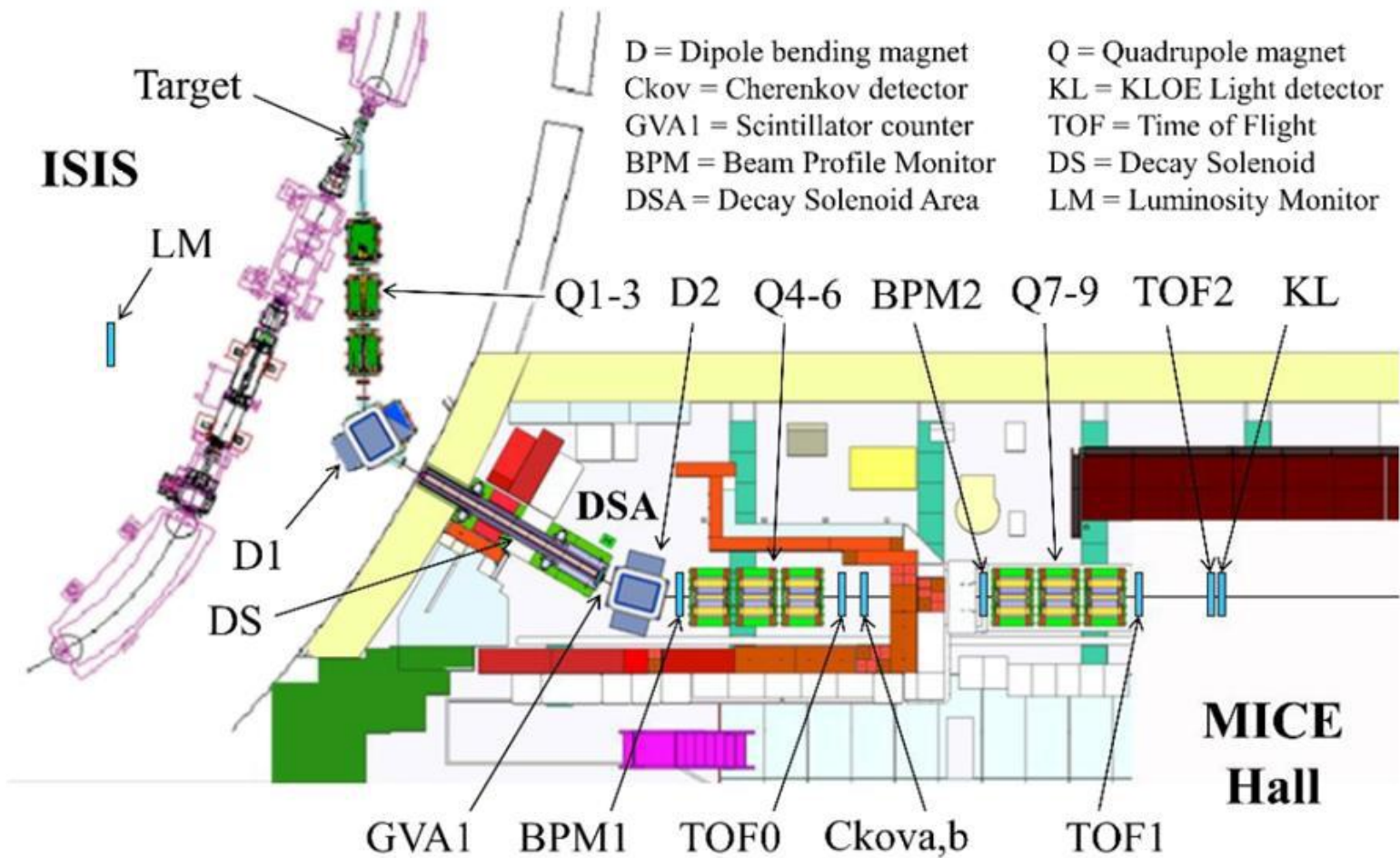
2 Dipoles

1 Superconducting 'Decay Solenoid'

MICE itself:

Step VI contains 16 superconducting solenoids

Plus additional detectors, and considerable infrastructure to support the experiment.



Top view of the MICE beam line with its instrumentation, as used in Step I.

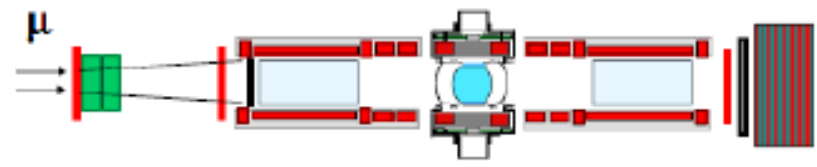
Provisional MICE SCHEDULE
update: October 2012

Run date:



STEP I

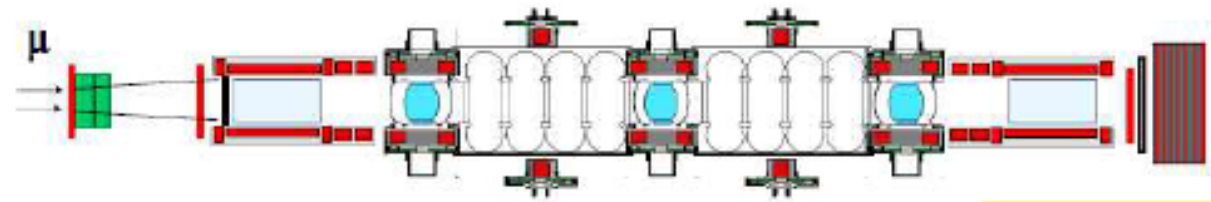
EMR run Q1-Q2 2013



STEP IV

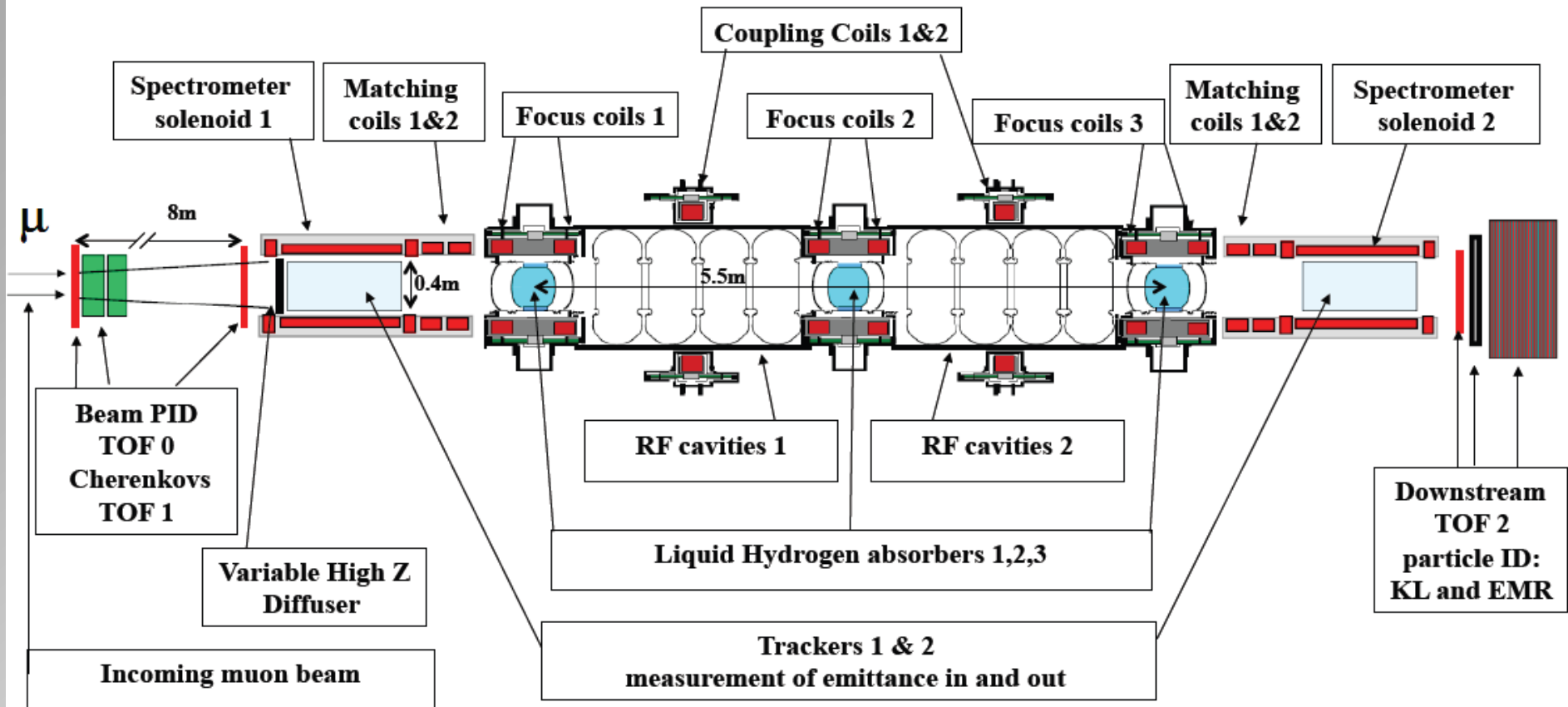
Q2 2014
till
Q4 2015

Under construction:



STEP VI

target date Q3 2018
Step V run possible Q3 2017



Overview of MICE

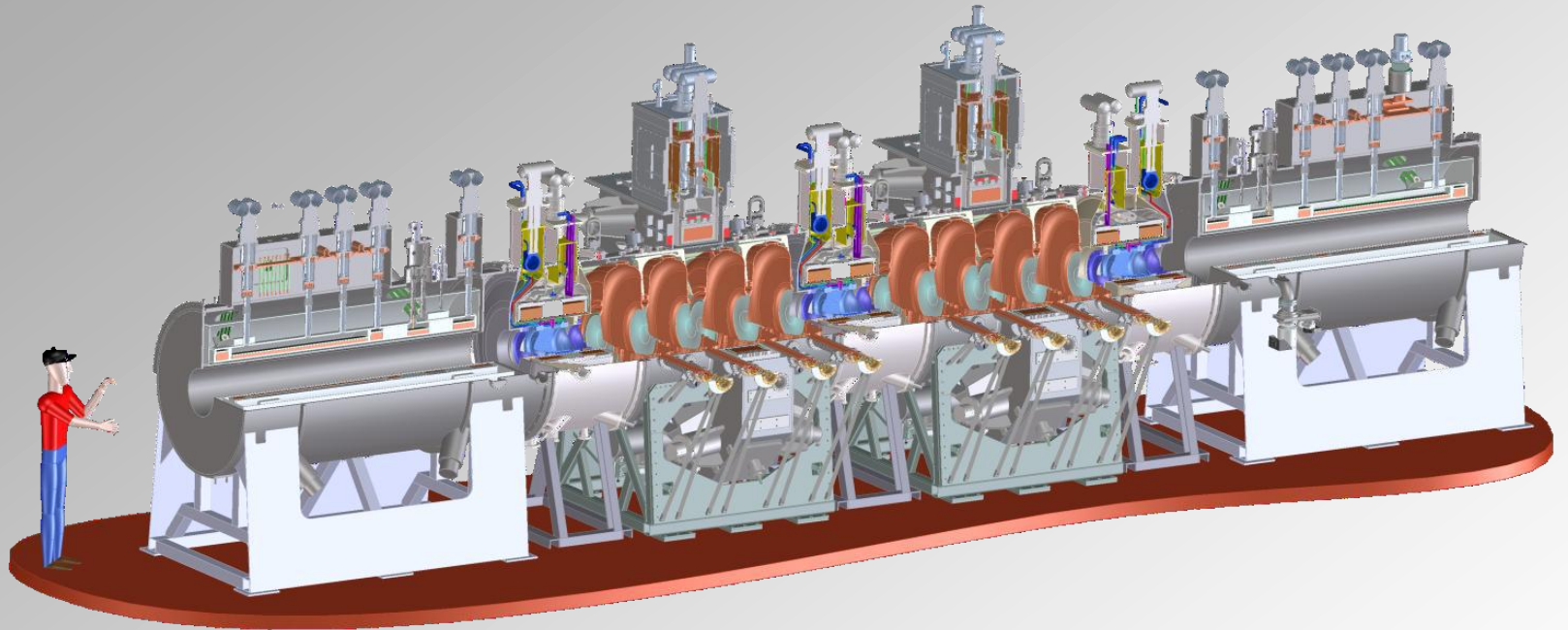
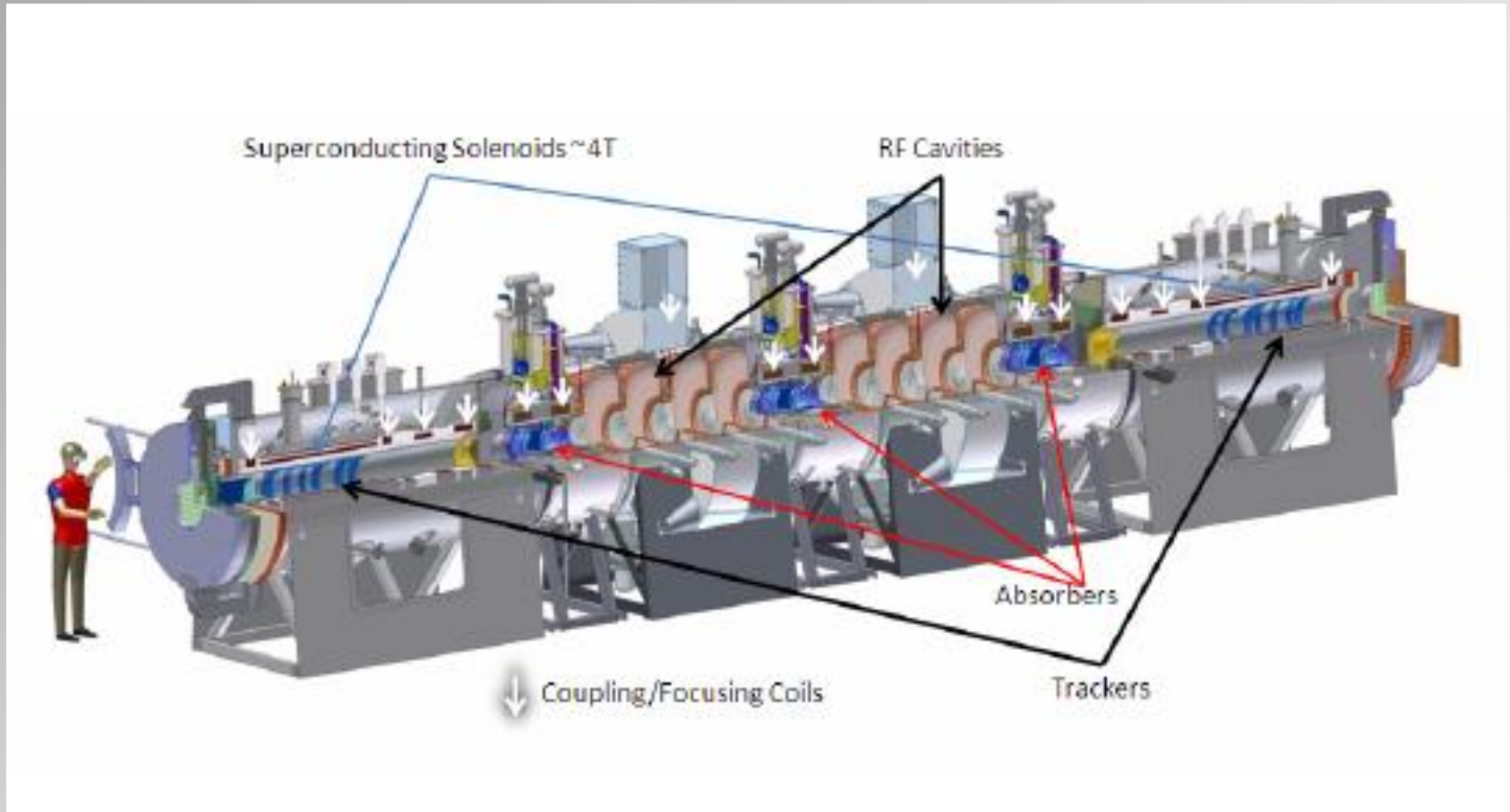


Illustration showing a completed step IV cooling channel. None of the external detectors and surrounding infrastructure are shown



Magnets

The MICE Magnets



The MICE Magnets

Solenoid Mode

Values taken from Technical Reference Document which is slightly out of date

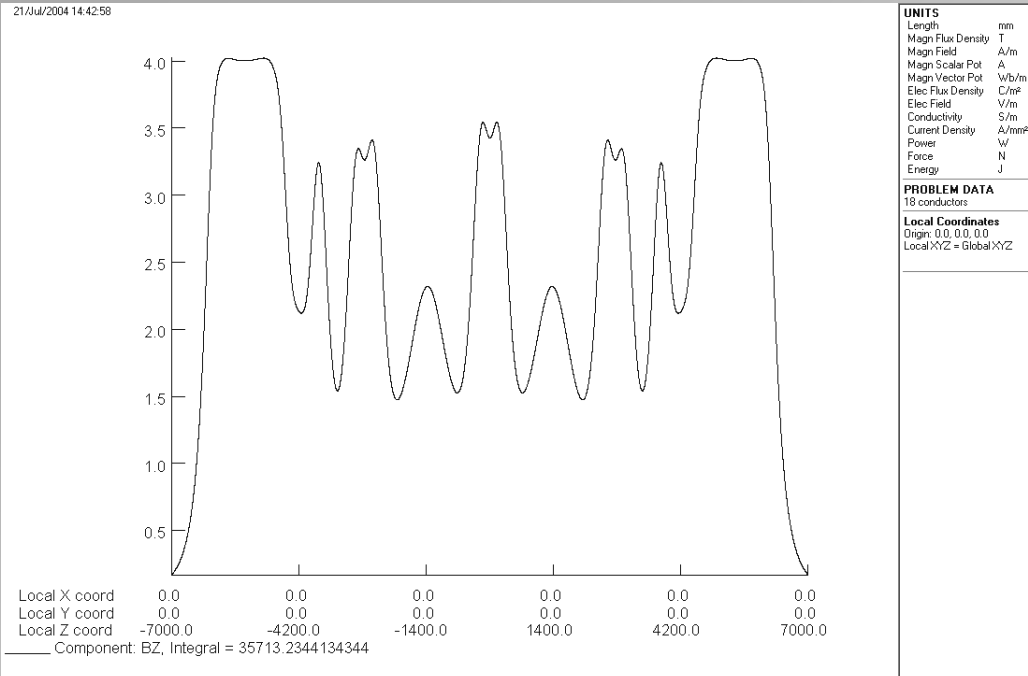
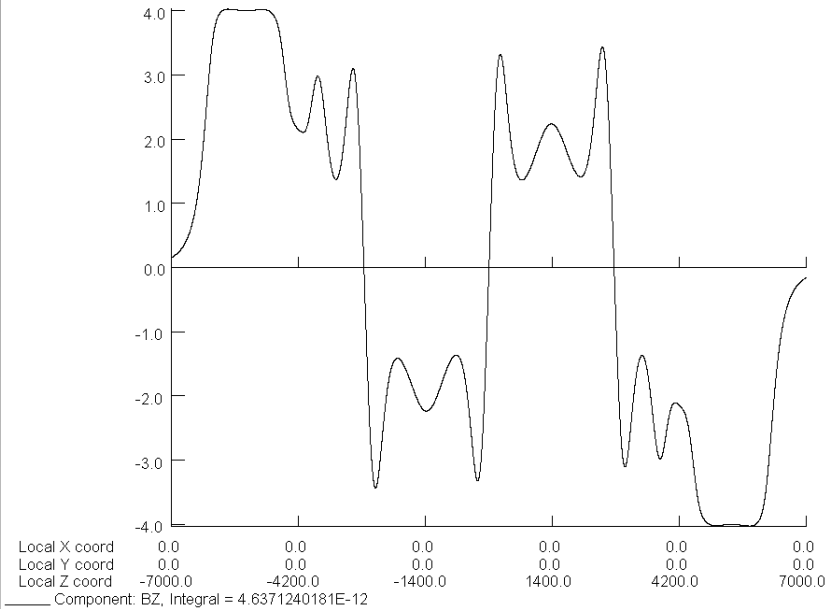


Table 4.1-3. Various Operating Cases for MICE Channel Operating in the Non-flip Mode. The average muon momentum p , beta at the absorber β , the spectrometer field B and the absolute value of the current density J in the coils in the full MICE channel under various operating conditions.

Parameter	Case 1	Case 2	Case 3	Case 4	Case 5
Average p (MeV/c)	200	240	200	200	200
Absorber β (cm)	42	42	25	15	7
Spectrometer B (T)	4.0	4.0	4.0	3.4	2.8
Focus J (A mm ⁻²)	59.52	71.42	79.59	97.62	112.76
Coupling J (A mm ⁻²)	87.41	104.89	79.14	68.90	44.48
Match #1 J (A mm ⁻²)	61.80	71.31	62.62	55.52	44.26
Match #2 J (A mm ⁻²)	54.82	65.62	34.67	29.96	16.32
End Coil #1 J (A mm ⁻²)	62.80	60.39	64.01	65.21	67.63
Centre J (A mm ⁻²)	63.49	63.49	63.49	63.49	63.49
End Coil #2 J (A mm ⁻²)	68.23	68.23	68.23	68.23	68.23

The MICE Magnets

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UNITS
 Length mm
 Magn Flux Density T
 Magn Field A/m
 Magn Scalar Pot A
 Magn Vector Pot Wb/m
 Elec Flux Density C/m²
 Elec Field V/m
 Conductivity S/m
 Current Density A/mm²
 Power W
 Force N
 Energy J

PROBLEM DATA
 18 conductors

Local Coordinates
 Origin: 0.0, 0.0, 0.0
 Local XYZ = Global XYZ

Flip Mode

Values taken from Technical Reference Document which is slightly out of date

Table 4.1-2. Various Operating Cases for MICE Channel Operating in the Flip Mode. The average muon momentum p , beta at the absorber β , the spectrometer field B and the absolute value of the current density J in the coils in the full MICE channel under various operating conditions.

Parameter	Case 1	Case 2	Case 3	Case 4	Case 5
Average p (MeV/c)	200	240	200	170	140
Absorber β (cm)	42	42	25	15	7
Spectrometer B (T)	4.0	4.0	4.0	3.4	2.8
Focus J (A mm ⁻²)	113.95	136.74	140.14	134.44	130.95
Coupling J (A mm ⁻²)	96.21	115.45	87.41	61.91	27.52
Match #1 J (A mm ⁻²)	56.30	66.82	54.71	42.05	21.55
Match #2 J (A mm ⁻²)	66.79	73.25	57.92	38.90	30.34
End Coil #1 J (A mm ⁻²)	62.80	61.59	62.80	54.41	45.65
Centre J (A mm ⁻²)	64.44	64.44	64.44	54.77	45.11
End Coil #2 J (A mm ⁻²)	67.11	67.11	67.11	57.04	46.98



The MICE Magnets

The MICE superconducting magnets were designed without return yokes.
(circa 2000~2004?)

Reasons for these not having return yokes...

(some speculation here as no-one is really holding their hand up)

- Cost
- Non distortion of magnetic field within MICE?
- Simulation results at the time showed that external field generated from these magnets was not going to be a problem.
- Others?

At this stage the reason is irrelevant. It's a problem that we have whatever the reason and it's a problem that we urgently need to solve...



Initial Simulation Work

About a year ago Mike Courthold and Vicky Bayliss (RAL) started to run some simulations that challenged the next-to-last assertion that I made on the previous slide.

It appears that the air fields produced by the MICE magnets were of sufficient magnitude to be of concern. There is a clear risk to the reliable functioning of a significant amount of equipment within the MICE hall and beyond the experimental hall's walls.

Defining the Problem

Since then much of the work done has to been to try and ascertain:

- Do we really have a problem and if so how big is it?
- What areas of the experimental hall are particularly affected?
- What items are particularly affected?
- Are there areas of the experimental hall that are not so badly affected by stray field and is it ok to put equipment in those areas?
- Where equipment can't be moved, what is the effect of the field on that equipment and if necessary can it be mitigated?
- Can the field be mitigated with a retrofitted return yoke?



Defining the Problem

Our starting assumption was that everything in the Hall, and some way beyond the Hall walls will be affected by the MICE magnetic fields.

A catalogue of potentially affected systems was then made – it's a huge list and I won't show it here – but is available on-line.

This was only starting assumption, and I think we are already someway towards showing that some areas of the Hall are now safe for Step IV of the project.



Magnetic Modelling

I shall take a look at all of these in more detail over the forthcoming slides:

1) I've built a magnetic FEA model of the whole experimental Hall – This provides a guide as to a first feel of the what the field level is likely to be like in particular areas.

2) There has been a lot of effort put into designing a retro-fitted return yoke for step IV (and step VI) - Holger Witte – BNL

If it can be implemented this looks like the obvious solution but in parallel we have to consider the possibility of running the experiment and the ramifications of not having a return yoke.

Even with a return yoke there are certain systems that will still be in high field and so the return yoke does not mitigate the need for some analysis work.



Magnetic Modelling



3) Sub Modelling. Areas of the hall that need particular attention and cannot be modelled in a 'Hall Model.



Model Verification

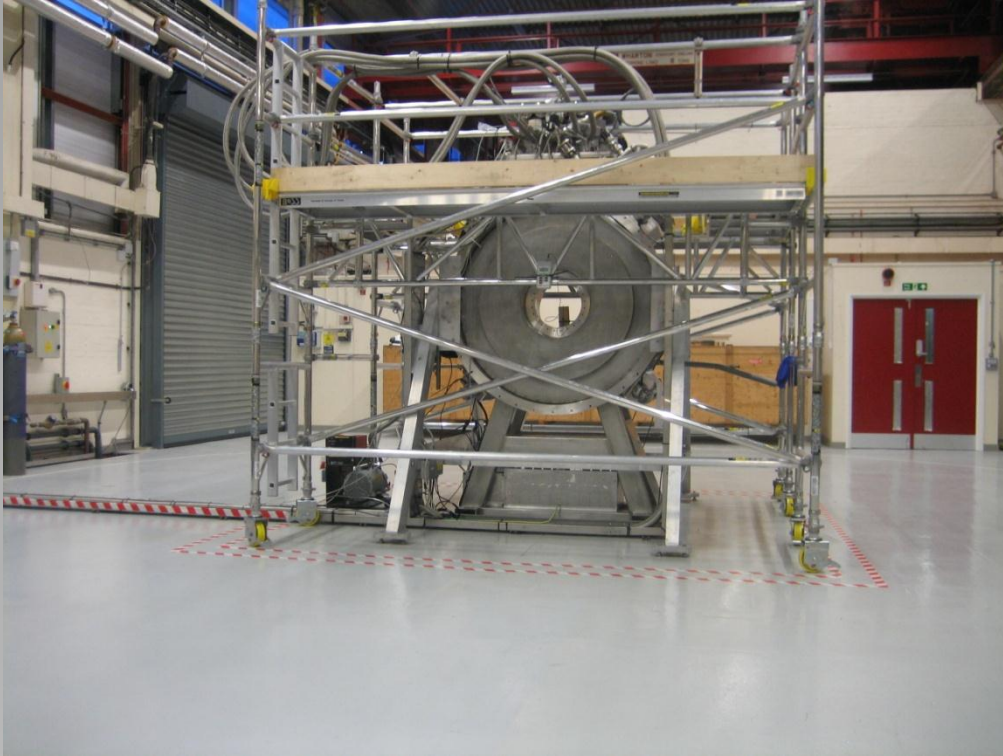
There is a clear desire to have some form of independent validation of these models!

R9 Testing

We're currently having an AFC magnet tested in R9 at RAL. The setup in R9 is being modelled by Vicky Bayliss (RAL) and extensive field measurements of equipment in situ (racks/compressors) will be taken .

The aim here is to tally the field measurements to the model and then to link this back to other models/sub-models. I'm lead to understand that this is no easy task.

AFC Magnet in R9



Cryomech Compressors and Controls in R9



Model Verification

Holger's Models

Holger Witte has built some independent models (OPERA FEA, OPERA Biot-Savart, COMSOL) that have demonstrated that the fields predicted at the West End of the MICE Hall by the Hall Model seem to be reasonable.

Holger has indicated that the meshing resolution in the Hall model is probably not good enough to give accurate results if we were to include finer levels of detail in the model.

I won't cover the details of his findings here as this would be another presentation in itself but I can provide you with copies of these presentations later if desired.



(1) Hall Model

There is a clear need understand what is happening in various locations of the MICE hall in good detail (accuracy) but without knowing the local field it is difficult to generate localised models.

The primary aim of the Hall model was to:

- Give an indication of what the field is in a particular area of the MICE Hall.
- Tell us whether the field is uniform in that area.
- If the field is not uniform then the Hall model can provide us with a data set of boundary fields that can be plugged into various local sub-models.

The last point has been shown in principle but not yet put into practice.



(1) Hall Model

The MICE Hall model contains a reasonably realistic representation of the structural iron contained within the MICE Hall itself. Other structures that are not made of iron but provide useful reference structures (i.e. walls and floors etc have also been added)

The structural iron in the MICE Hall has no symmetry and so a full 3D model is required.

In terms of the code itself it was fairly clear from the outset that a Hall model was going to be a big task and writing one long piece of .comi script was going to end in tears...

The Hall model is component based, so components can be turned on and off at will in the .comi code and in principle it should still mesh and run. This has significantly speeded up coding/debugging.

At the moment no studies on what the effect of turning individual components off has on the field , so I tend to only run models with all of the components turned on. In light of recent findings it's not clear that such a study would be productive.

(1) Hall Model

After the iron was added to the hall there was a great temptation on my behalf to push the model to see what meshing resolution I could achieve whilst keeping the solve time tractable. (Call this inexperience and no data yet on the model's validity.)

Our first 'study' with the Hall model involved placing some racks in the Hall model and increased the meshing resolution in those areas to see how those racks affected the fields. Interesting results but...

Later, independent studies by Holger indicated that the meshing resolution in the Hall model is not high enough to give accurate results at the level of detail that was being modelled.

At this point it is probably fair to say that the Hall model is probably serving its purpose – **subject to model validation** - it is providing us with first estimates of background fields given realistic estimates of iron content within the Hall.



(1) Hall Model - Website

The development of the Hall model has been reasonably well documented (at least by my standards) and a lot of information can be found at

http://www.hep.shef.ac.uk/research/mice/opera_models/

Notes

Drawings

comi Script

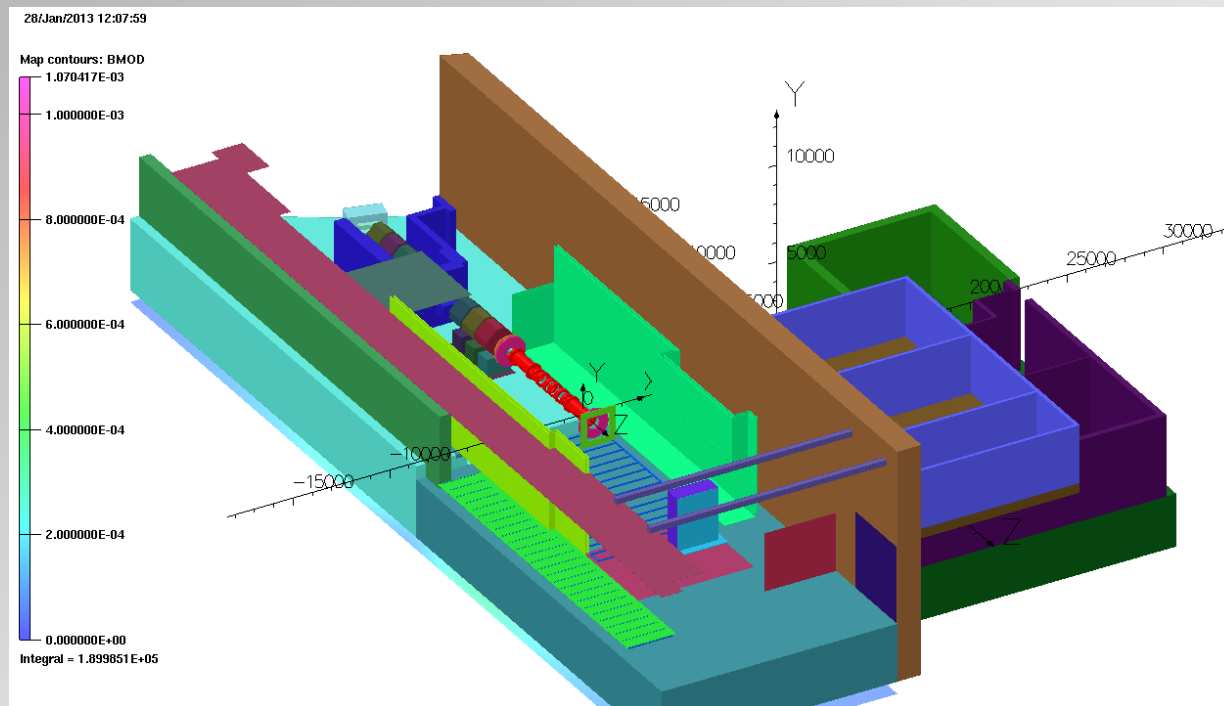
(Results)

This might be a useful source of information to those involved in the modelling.

(1) Hall Model – Model 52

This is one of the latest models – if we can view this model in OPERA then I can zoom in and give you a virtual tour...

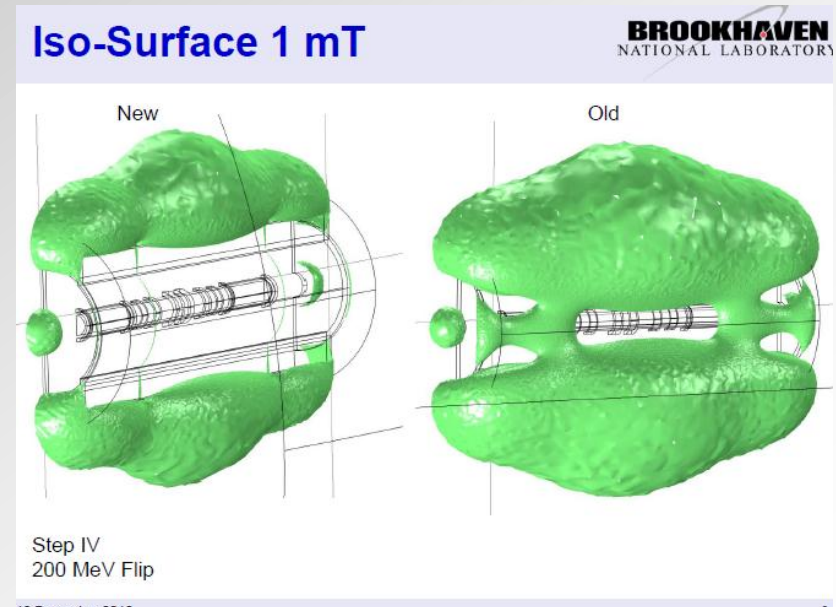
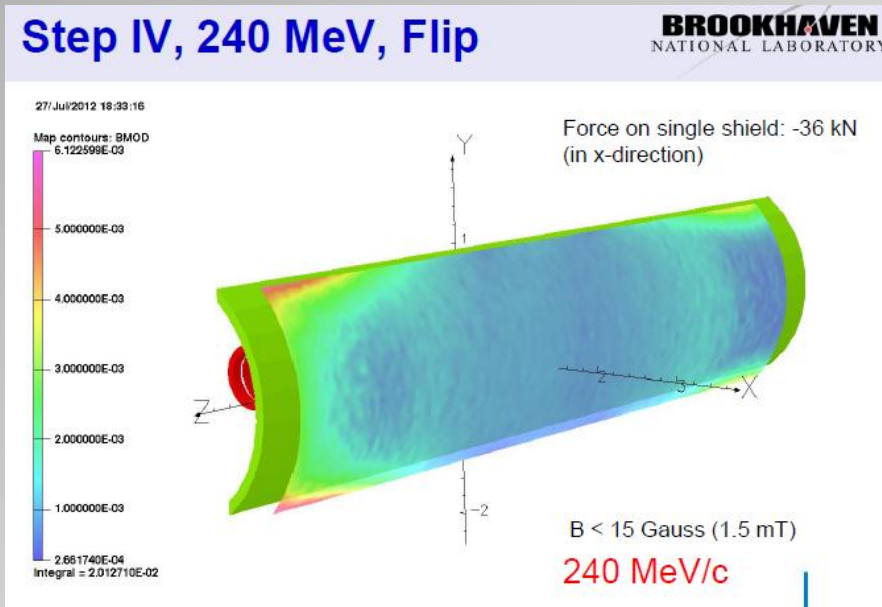
Also a good point to visit the modelling website



(2) Return Yoke

Holger Witte (BNL) has been working on the design of a retro-fitted return yoke to the cooling channel for step IV.

We now have an outline magnetic solution for step IV – the devil is in the engineering detail which is now being worked upon . These example slides have been taken from Holger’s presentations to illustrate the principle – details may change.



Early development of idea

13/03/2013

Return yoke connected to end plates and with addition of vertical ‘flanges’ 27



(3) Sub Modelling

The areas of particular interest include:

Tracker

Sub station

Quads

Better Rack model

Transformer in Trench

Racks behind North Shield Wall.

The idea here is to model these areas in much higher resolution than is achievable with the hall model. We may use the hall model to provide boundary fields for these sub models, or we could use it to estimate the peak fields seen within these volumes.



Why we need help

The hall model is a fairly complex model which has raised a number of questions over how we can benchmark the model in such a way that the results from the model can be trusted. We need a model that we can believe in so that we can take the project forward.

We have ideas on how this can be done but this project is time critical and we could spend a lot of time (and have been) learning how to do this, some expert advice could save us a lot of time and effort.

We have compiled a document which addresses most of our immediate concerns for your consideration. Some of the questions on the list may not be easy to answer... others may be.